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GENERALIZATION OF DARBO'S FIXED POINT THEOREM VIA NEW CONTRACTION

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Abstract. In the present paper, using a new contraction on Banach space, we generalize Darbo's fixed point theorem and also some fixed point theorems which were recently proved by some authors [2, 11].

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1. INTRODUCTION

In 1955, Darbo [7] proved the fixed point theorem for α -set contraction (i.e., $\alpha(T(A)) \leq k\alpha(A)$ with $k \in [0, 1)$) on a closed, bounded and convex subset of a Banach space in terms of the measure of noncompactness. Since then many generalizations and extensions of this theorem have appeared; see for example [2, 3, 4, 6, 8, 9, 10, 11, 12].

The aim of this paper is to generalize Darbo's fixed point theorem and also a result of Aghajani et al [2] using the following new contraction:

$$\varphi(\overline{\text{conv}}(TA)) \leq \varphi(A) - \phi(\sigma(A)) \quad \forall A \in P(\Omega),$$

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where T is a continuous mapping from Ω to itself, with Ω is a closed, bounded and convex subset of a Banach space, $P(\Omega)$ is the set of subsets of Ω , $\overline{\text{conv}}$ is the closed convex hull, $\sigma, \varphi: P(\Omega) \rightarrow \mathbb{R}^+$ are mappings, such that σ verifies some properties of a measure of noncompactness and $\phi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a lower semicontinuous function such that $\phi(0) = 0$ and $\phi(t) > 0$ for all $t > 0$. Moreover, we derive from this theorem some consequences which are a generalizations of Darbos fixed point theorem and a Samadi-Ghaemi's result [11].

2. PRELIMINARIES

At the beginning we provide notations and some auxiliary facts which will be needed in the sequel. To this end, assume that X is a given Banach space. If B is a subset of X then the symbols \bar{B} and $\text{conv}(B)$ stand for the closure and the convex hull of B , respectively. Moreover, let \mathfrak{M}_X be the family of all nonempty and bounded subsets of X and \mathfrak{N}_X be its subfamily consisting of all relatively compact sets.

We mention the following definition of the measure of noncompactness, given in [5].

Definition 2.1. A mapping $\mu: \mathfrak{M}_X \rightarrow [0, \infty)$ is said to be a measure of noncompactness in X if it satisfies the following conditions:

- (i) The family $\ker \mu = \{A \in \mathfrak{M}_X : \mu(A) = 0\}$ is nonempty and $\ker \mu \subseteq \mathfrak{N}_X$.
- (ii) $A \subseteq B \Rightarrow \mu(A) \leq \mu(B)$.
- (iii) $\mu(\bar{A}) = \mu(A) = \mu(\text{conv}(A))$.
- (iv) $\mu(\lambda A + (1 - \lambda)B) \leq \lambda \mu(A) + (1 - \lambda)\mu(B)$, for $\lambda \in [0, 1]$.
- (v) If (A_n) is a sequence of closed sets from \mathfrak{M}_X such that $A_{n+1} \subseteq A_n$ for $(n = 1, 2, \dots)$ and if $\lim_{n \rightarrow +\infty} \mu(A_n) = 0$, then the set $A_\infty = \bigcap_{n=1}^{\infty} A_n \neq \emptyset$.

The family $\ker \mu$ defined in axiom (i) is called the kernel of the measure of noncompactness. Darbos fixed point theorem is a generalization of Schauders fixed point theorem.

Theorem 2.2 (Schauder [1]). *Let Ω be a nonempty, compact and convex subset of a Banach space X . Then each continuous mapping $T: \Omega \rightarrow \Omega$ has at least one fixed point in Ω .*

In the following, we state a fixed point theorem of Darbo type proved by Banaś and Goebel [5].

Theorem 2.3. *Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous mapping. Assume that there exists a constant $k \in [0, 1)$ such that*

$$(1) \quad \mu(TA) \leq k\mu(A)$$

for any nonempty subset A of Ω , where μ is a measure of noncompactness defined in X . Then T has a fixed point in Ω .

3. MAIN RESULTS

The main result of the present paper is the following fixed point theorem which is a generalization of Darbo's fixed point theorem.

Theorem 3.1. *Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous mapping. Assume that :*

$$(2) \quad \varphi(\overline{\text{conv}}(TA)) \leq \varphi(A) - \phi(\sigma(A))$$

for any nonempty subset A of Ω , where $\sigma, \varphi : P(\Omega) \rightarrow [0, +\infty)$ are mappings such that σ satisfies the axioms (i), (ii) and (v) in the Definition 2.1 and $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a lower semicontinuous function, $\phi(0) = 0$ and $\phi(t) > 0$ for all $t > 0$. Then T has a fixed point in Ω .

Proof. We define the sequence $(\Omega_n)_n$ as follows

$$(3) \quad \begin{cases} \Omega_0 := \Omega, \\ \Omega_n := \overline{\text{conv}}(T\Omega_{n-1}), \quad n = 1, 2, \dots \end{cases}$$

by induction, we observe easily that

$$(4) \quad \Omega_{n+1} \subseteq \Omega_n, \quad n = 0, 1, 2, \dots$$

we put $a_n = \varphi(\Omega_n)$, from the inequality (2) we have $\varphi(\Omega_n) - \varphi(\overline{\text{conv}}(T\Omega_n)) \geq 0$, and we obtain

$$a_{n+1} = \varphi(\Omega_{n+1}) = \varphi(\overline{\text{conv}}(T\Omega_n)) \leq \varphi(\Omega_n) = a_n,$$

therefore $(a_n)_n$ and $(\sigma(\Omega_n))_n$ are a decreasing sequences in \mathbb{R}^+ , then there exist a real numbers a and r such that $a_n \xrightarrow{n \rightarrow +\infty} a$ and $\sigma(\Omega_n) \xrightarrow{n \rightarrow +\infty} r$. On the other hand, we have

$$\varphi(\overline{\text{conv}}(T\Omega_n)) \leq \varphi(\Omega_n) - \phi(\sigma(\Omega_n)),$$

this implies that $a_{n+1} \leq a_n - \phi(\sigma(\Omega_n))$, we obtain

$$(5) \quad \limsup_{n \rightarrow +\infty} a_{n+1} \leq \limsup_{n \rightarrow +\infty} a_n - \liminf_{n \rightarrow +\infty} \phi(\sigma(\Omega_n)).$$

This yields $a \leq a - \phi(r)$. Consequently $\phi(r) = 0$ so $r = 0$.

Hence we deduce that

$$(6) \quad \lim_{n \rightarrow +\infty} \sigma(\Omega_n) = 0.$$

From the property (v) in the Definition 2.1, the set $\Omega_\infty := \bigcap_{n=1}^{\infty} \Omega_n$ is nonempty. Moreover, for every $n = 0, 1, 2, \dots$, we have

$$(7) \quad \Omega_\infty \subseteq \Omega_n,$$

which implies that

$$\sigma(\Omega_\infty) \leq \sigma(\Omega_n), \quad n = 0, 1, 2, \dots$$

Passing to the limit as $n \rightarrow \infty$ and using (6), we obtain

$$(8) \quad \sigma(\Omega_\infty) = 0,$$

which implies from the property (i) in the Definition 2.1 that $\overline{\Omega_\infty} = \Omega_\infty$ is compact.

Moreover, since each Ω_n is convex, Ω_∞ is convex, and

$$T\Omega_\infty \subseteq T\Omega_n \subseteq \overline{\text{conv}}(T\Omega_n) = \Omega_{n+1} \subseteq \Omega_n, \quad n = 0, 1, 2, \dots$$

Then $T: \Omega_\infty \rightarrow \Omega_\infty$ is well defined. By Theorem 2.2, T has a fixed point in Ω . □

Remark 3.2. By taking ϕ the identity function, $\sigma = \mu$ and $\varphi = (\frac{1}{1-k})\mu$ where μ is a measure of noncompactness and $k \in [0, 1)$, in Theorem 3.1 we obtain Darbo's fixed point theorem.

As a consequence of Theorem 3.1, we have the following result due to Aghajani et al [3].

Theorem 3.3. *Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous operator such that*

$$(9) \quad \psi(\mu(TA)) \leq \psi(\mu(A)) - \phi(\mu(A))$$

for any nonempty subset A of Ω , where μ is an arbitrary measure of noncompactness and $\phi, \psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ are a given functions such that ϕ is lower semicontinuous and ψ is continuous on \mathbb{R}^+ . Moreover, $\phi(0) = 0$ and $\phi(t) > 0$ for $t > 0$. Then T has at least one fixed point in Ω .

Proof. By taking $\sigma = \mu$ and $\varphi = \psi \circ \mu$ where μ is a measure of noncompactness and $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a continuous function, in Theorem 3.1 we obtain Theorem 3.3. \square

Now, we give the following corollaries of Theorem 3.1.

Corollary 3.4. *Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous mapping. Assume that :*

$$(10) \quad \varphi(\overline{\text{conv}}(TA)) \leq \varphi(A) - \sigma(A)$$

for any nonempty subset A of Ω , where $\sigma, \varphi : P(\Omega) \rightarrow [0, +\infty)$ are a mappings such that σ satisfies the axioms (i), (ii) and (v) in the Definition 2.1. Then T has a fixed point in Ω .

Corollary 3.5. *Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous mapping such that*

$$(11) \quad \mu(TA) \leq \eta(\mu(A))$$

for any nonempty subset A of Ω , where μ is a measure of noncompactness defined in X and $\eta : [0, +\infty) \rightarrow [0, +\infty)$ is a mapping such that $\eta(t) < t$, for each $t > 0$ and $\frac{\eta(t)}{t}$ is non-decreasing. Then T has a fixed point in Ω .

Proof. Taking $\sigma = \mu$ and $\varphi(A) = \frac{\mu(A)}{1 - \frac{\eta(\mu(A))}{\mu(A)}}$, if $\mu(A) \neq 0$ and otherwise $\varphi(A) = 0$. Then (11) shows that

First case, if $\mu(A) \neq 0$, we have

$$(12) \quad \mu(TA) \leq \mu(A) - \left[1 - \frac{\eta(\mu(A))}{\mu(A)} \right] \mu(A),$$

it means that

$$(13) \quad \frac{\mu(TA)}{1 - \frac{\eta(\mu(A))}{\mu(A)}} \leq \frac{\mu(A)}{1 - \frac{\eta(\mu(A))}{\mu(A)}} - \mu(A).$$

Since $\frac{\eta(t)}{t}$ is non-decreasing and $\mu(TA) < \mu(A)$, we have

a) If $\mu(TA) \neq 0$, then

$$(14) \quad \frac{\mu(TA)}{1 - \frac{\eta(\mu(TA))}{\mu(TA)}} \leq \frac{\mu(A)}{1 - \frac{\eta(\mu(A))}{\mu(A)}} - \mu(A),$$

so

$$(15) \quad \varphi(\overline{\text{conv}}TA) \leq \varphi(A) - \mu(A).$$

b) If $\mu(TA) = 0$, we have $\varphi(\overline{\text{conv}}(TA)) = \mu(\overline{\text{conv}}(TA)) = 0$ and

$$\begin{aligned} -\frac{\eta(\mu(A))}{\mu(A)} \leq 0 &\Rightarrow 1 - \frac{\eta(\mu(A))}{\mu(A)} \leq 1 \\ &\Rightarrow 1 \leq \frac{1}{1 - \frac{\eta(\mu(A))}{\mu(A)}} \\ &\Rightarrow \mu(A) \leq \frac{\mu(A)}{1 - \frac{\eta(\mu(A))}{\mu(A)}} \\ &\Rightarrow 0 \leq \frac{\mu(A)}{1 - \frac{\eta(\mu(A))}{\mu(A)}} - \mu(A) \\ &\Rightarrow \varphi(\overline{\text{conv}}(TA)) \leq \varphi(A) - \mu(A). \end{aligned}$$

Seconde case, if $\mu(A) = 0$, from the properties (i), (ii) and the fact that T is continuous, we have $\mu(TA) = 0$, so

$$\varphi(\overline{\text{conv}}TA) \leq \varphi(A) - \mu(A).$$

Then by Corollary 3.4, T has a fixed point in Ω . □

Remark 3.6. By taking $\eta(t) = kt$ for all $t \in [0, \infty)$ with $k \in [0, 1)$, then Corollary 3.5 is a generalization of Darbo's fixed point theorem.

Corollary 3.7. Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T : \Omega \rightarrow \Omega$ be a continuous mapping such that

$$(16) \quad \mu(TA) \leq \mu(A) - \theta(\mu(A))$$

for any nonempty subset A of Ω , where μ is a measure of noncompactness defined in X and $\theta: (0, +\infty) \rightarrow (0, +\infty)$ is a mapping such that, $\frac{\theta(t)}{t}$ is non-increasing. Then T has a fixed point in Ω .

Proof. Let $\eta(t) = t - \theta(t)$, for each $t > 0$. Then $\eta(t) < t$, for each $t > 0$ and $\frac{\eta(t)}{t} = 1 - \frac{\theta(t)}{t}$ is non-decreasing. Thus, the result is obtained by Corollary 3.5. \square

Remark 3.8. By taking $\theta(t) = (1 - k)t$ for all $t \in [0, \infty)$ with $k \in [0, 1)$, then Corollary 3.7 is a generalization of Darbo's fixed point theorem.

The following corollary shows the same result due to Samadi and Ghaemi [11].

Corollary 3.9. Let Ω be a nonempty, bounded, closed and convex subset of a Banach space X and let $T: \Omega \rightarrow \Omega$ be a continuous mapping such that

$$(17) \quad \mu(TA) \leq \phi(\mu(A))\mu(A)$$

for any nonempty subset A of Ω , where μ is a measure of noncompactness defined in X and $\phi: [0, +\infty) \rightarrow [0, 1)$ is a non-decreasing mapping. Then T has a fixed point in Ω .

Proof. Let $\eta(t) = \phi(t)t$ for all $t > 0$. Then $\eta(t) < t$ for all $t > 0$ and $\frac{\eta(t)}{t} = \phi(t)$ is non-decreasing. By assumption $\mu(TA) \leq \phi(\mu(A))\mu(A) = \eta(\mu(A))$ for all $A \subseteq \Omega$, therefore by Corollary 3.5, T has a fixed point. \square

Remark 3.10. By taking $\phi(t) = k$ for all $t \in [0, \infty)$ with $k \in [0, 1)$, then Corollary 3.9 is a generalization of Darbo's fixed point theorem.

Conflict of Interests

The authors declare that there is no conflict of interests.

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